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Vishay Semiconductors

# Fully Integrated Proximity and Ambient Light Sensor With Infrared Emitter, I<sup>2</sup>C Interface, and Interrupt Function



# <u>3D Models</u> <u>Design Tools</u> <u>D</u>

## DESCRIPTION

VCNL4040 integrates a proximity sensor (PS), ambient light sensor (ALS), and a high power IRED into one small package. It incorporates photodiodes, amplifiers, and analog to digital converting circuits into a single chip by CMOS process. The 16-bit high resolution ALS offers excellent sensing capabilities with sufficient selections to fulfill most applications whether dark or high transparency lens design. High and low interrupt thresholds can be programmed for both ALS and PS, allowing the component to use a minimal amount of the microcontrollers resources.

The proximity sensor features an intelligent cancellation scheme, so that cross talk phenomenon is eliminated effectively. To accelerate the PS response time, smart persistence prevents the misjudgment of proximity sensing but also keeps a fast response time. In active force mode, a single measurement can be requested, allowing another good approach for more design flexibility to fulfill different kinds of applications with more power saving.

The patented Filtron<sup>TM</sup> technology achieves ambient light spectral sensitivity closest to real human eye response and offers the best background light cancellation capability (including sunlight) without utilizing the microcontrollers' resources. VCNL4040 provides an excellent temperature compensation capability for keeping output stable under various temperature configurations. ALS and PS functions are easily set via the simple command format of I<sup>2</sup>C (SMBus compatible) interface protocol. Operating voltage ranges from 2.5 V to 3.6 V. VCNL4040 is packaged in a lead (Pb)-free 8-pin molding package, which offers the best market-proven reliability quality.

### FEATURES

- Package type: surface-mount
- Dimensions (L x W x H in mm): 4.0 x 2.0 x 1.1
- Integrated modules: infrared emitter (IRED), ambient light sensor (ALS), proximity sensor (PS), and signal conditioning IC
- Operates ALS and PS in parallel structure
- Filtron<sup>TM</sup> technology adoption for robust background light cancellation
- FREE <u>GREEN</u> (5-2008)

ROHS COMPLIANT

HALOGEN

- Temperature compensation: -40 °C to +85 °C
- Low power consumption I<sup>2</sup>C (SMBus compatible) interface
- Floor life: 168 h, MSL 3, according to J-STD-020
- Output type: I<sup>2</sup>C bus (ALS / PS)
- Operation voltage: 2.5 V to 3.6 V
- Material categorization: for definitions of compliance please see <u>www.vishay.com/doc?99912</u>

### **PROXIMITY FUNCTION**

- Immunity to red glow (940 nm IRED)
- Programmable IRED sink current
- Intelligent cancellation to reduce cross talk phenomenon
- Smart persistence scheme to reduce PS response time
- Selectable for 12- / 16-bit PS output data

### AMBIENT LIGHT FUNCTION

- High accuracy of ALS ±10 %
- Fluorescent light flicker immunity
- · Spectrum close to real human eye responses
- Selectable maximum detection range (819 / 1638 / 3277 / 6553) lux with highest sensitivity 0.0125 lux/step

### INTERRUPT

- Programmable interrupt function for ALS and PS with upper and lower thresholds
- Adjustable persistence to prevent false triggers for ALS and PS

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### APPLICATIONS

- Handheld device
- Notebook, tablet PC
- Consumer device
- Industrial application







PROD	UCT	SUM	MAR	Y

PRODUCI	RODUCT SUMMARY											
PART NUMBER	OPERATING RANGE (mm)	OPERATING VOLTAGE RANGE (V)	I <sup>2</sup> C BUS VOLTAGE RANGE (V)	IRED PULSE CURRENT <sup>(1)</sup> (mA)	AMBIENT LIGHT RANGE (lx)	AMBIENT LIGHT RESOLUTION (Ix)	OUTPUT CODE	ADC RESOLUTION PROXIMITY / AMBIENT LIGHT				
VCNL4040	0 to 200	2.5 to 3.6	1.8 to 3.6	200	0.0125 to 6553	0.0125	16 bit, I <sup>2</sup> C	16 bit / 16 bit				

#### Note

<sup>(1)</sup> Adjustable through I<sup>2</sup>C interface

ORDERING INFORMATION									
ORDERING CODE	PACKAGING	VOLUME <sup>(1)</sup>	REMARKS						
VCNL4040M3OE		MOQ: 2500 pcs	4.0 mm x 2.0 mm x 1.1 mm						
VCNL4040M3OE-H3 <sup>(2)</sup>	Tape and reel	MOO: 1500 peo	4.34 mm x 2.35 mm x 3.25 mm						
VCNL4040M3OE-H5 <sup>(2)</sup>		MOQ: 1500 pcs	4.34 mm x 2.35 mm x 3.65 mm						

#### Notes

<sup>(1)</sup> MOQ: minimum order quantity

<sup>(2)</sup> The interposers are necessary when the component needs to be brought closer to a cover glass and the customers mechanical stack up does not allow for this with the standard height component (VCNL4040M3OE)

ABSOLUTE MAXIMUM RATINGS (T <sub>amb</sub> = 25 °C, unless otherwise specified)										
PARAMETER	TEST CONDITION	SYMBOL	MIN.	MAX.	UNIT					
Supply voltage		V <sub>DD</sub>	2.5	3.6	V					
Operation temperature range		T <sub>amb</sub>	-40	+85	°C					
Storage temperature range		T <sub>stg</sub>	-40	+100	°C					

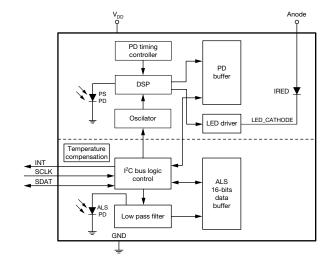
<b>RECOMMENDED OPERATING CONDITIONS</b> (T <sub>amb</sub> = 25 °C, unless otherwise specified)										
PARAMETER	TEST CONDITION	SYMBOL	MIN.	MAX.	UNIT					
Supply voltage		V <sub>DD</sub>	2.5	3.6	V					
Operation temperature range		T <sub>amb</sub>	-40	+85	°C					
I <sup>2</sup> C bus operating frequency		f <sub>(I2CCLK)</sub>	10	400	kHz					

PIN DESCRIPTIONS										
PIN ASSIGNMENT	SYMBOL	TYPE	FUNCTION							
1	GND	I	Ground							
2	CATHODE	I	Cathode (sensor) connection							
3	V <sub>DD</sub>	I	Power supply input							
4	ANODE	I	Anode for IRED							
5	CATHODE	I	Cathode (LED) connection							
6	INT	0	Interrupt pin							
7	SDAT	I / O (open drain)	I <sup>2</sup> C data bus data input / output							
8	SCLK	I	I <sup>2</sup> C digital bus clock input							





### **BLOCK DIAGRAM**



PARAMETER		TEST CONDITION	SYMBOL	MIN.	TYP.	MAX.	UNIT	
Supply voltage			V <sub>DD</sub>	2.5		3.6	V	
0		Excluded LED driving	I <sub>DD</sub>		300		μA	
Supply current		Light condition = dark, $V_{DD}$ = 3.3 V	I <sub>DD</sub> (SD)		0.2		μA	
I <sup>2</sup> C supply voltage			V <sub>PULL UP</sub>	1.8		3.6	V	
ALS shut down		ALS disable, PS enable	I <sub>ALSSD</sub>		200		μA	
PS shut down		ALS enable, PS disable	I <sub>PSSD</sub>		260		μA	
	Logic high		VIH	1.55			v	
12C aignal input	Logic low	V <sub>DD</sub> = 3.3 V	V <sub>IL</sub>			0.4	v	
I <sup>2</sup> C signal input	Logic high	N 0.6 M	V <sub>IH</sub>	1.4			V	
	Logic low	V <sub>DD</sub> = 2.6 V	VIL			0.4	v	
Peak sensitivity wavelength of ALS			λ <sub>p</sub>		550		nm	
Peak sensitivity wa	velength of PS		λ <sub>pps</sub>		940		nm	
Full ALS counts		16-bit resolution				65 535	steps	
Full PS counts		12-bit / 16-bit resolution				4096 / 65 535	steps	
ALS sensing tolera	nce	White LED light source				± 10	%	
Detectable	Minimum	I <sub>T</sub> = 640 ms, 1 step <sup>(1)(2)</sup>			0.0125			
intensity	Maximum	I <sub>T</sub> = 80 ms, 65 535 step <sup>(1)(2)</sup>			6553		lx	
ALS dark offset		I <sub>T</sub> = 80 ms, normal sensitivity <sup>(1)</sup>		0		3	steps	
PS detection range		Kodak white card		0		200	mm	
Operating tempera	ture range		T <sub>amb</sub>	-40		+85	°C	
Cathode (sensor) v	oltage			2.5		3.6	V	
IRED driving currer	ıt	(3)				200	mA	

#### Notes

 $^{(1)}\,$  Test condition:  $V_{DD}$  = 3.3 V, temperature: 25  $^{\circ}C$ 

<sup>(2)</sup> Maximum detection range to ambient light can be determined by ALS refresh time adjustment. Refer to table "ALS Resolution and Maximum Detection Range"

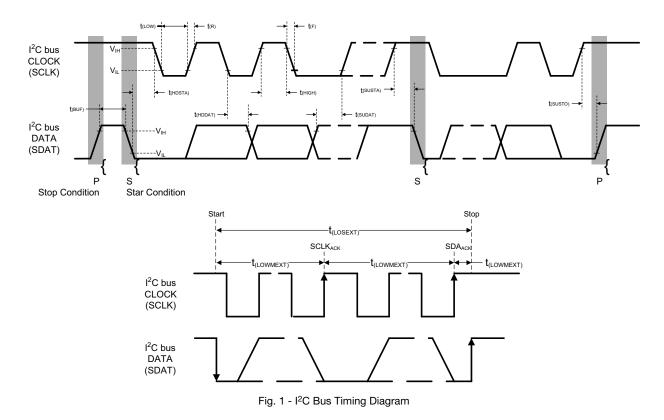
<sup>(3)</sup> Based on IRED on / off duty ratio = 1/40, 1/80, 1/160, and 1/320

# VCNL4040



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I <sup>2</sup> C BUS TIMING CHARACTERISTICS (T <sub>amb</sub> = 25 °C, unless otherwise specified)								
PARAMETER	SYMBOL	STANDA	RD MODE	FAST	UNIT			
PARAMETER	STINDUL	MIN.	MAX.	MIN.	MAX.			
Clock frequency	f <sub>(SMBCLK)</sub>	10	100	10	400	kHz		
Bus free time between start and stop condition	t <sub>(BUF)</sub>	4.7		1.3		μs		
Hold time after (repeated) start condition; after this period, the first clock is generated	t <sub>(HDSTA)</sub>	4.0		0.6		μs		
Repeated start condition setup time	t <sub>(SUSTA)</sub>	4.7		0.6		μs		
Stop condition setup time	t <sub>(SUSTO)</sub>	4.0		0.6		μs		
Data hold time	t <sub>(HDDAT)</sub>		3450		900	ns		
Data setup time	t <sub>(SUDAT)</sub>	250		100		ns		
I <sup>2</sup> C clock (SCK) low period	t <sub>(LOW)</sub>	4.7		1.3		μs		
I <sup>2</sup> C clock (SCK) high period	t <sub>(HIGH)</sub>	4.0		0.6		μs		
Clock / data fall time	t <sub>(F)</sub>		300		300	ns		
Clock / data rise time	t <sub>(R)</sub>		1000		300	ns		





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### PARAMETER TIMING INFORMATION

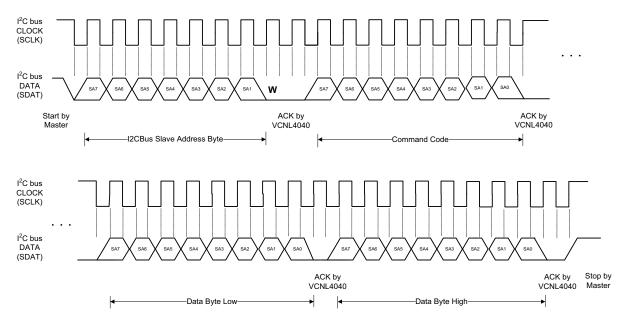


Fig. 2 - I<sup>2</sup>C Bus Timing for Sending Word Command Format

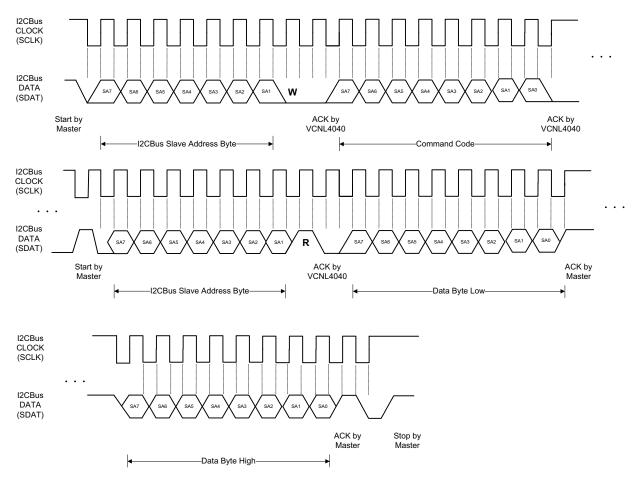


Fig. 3 - I<sup>2</sup>C Bus Timing for Receiving Word Command Format



## **TYPICAL PERFORMANCE CHARACTERISTICS** ( $T_{amb} = 25 \text{ °C}$ , unless otherwise specified)

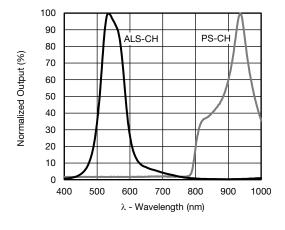


Fig. 4 - Normalized Spectral Response

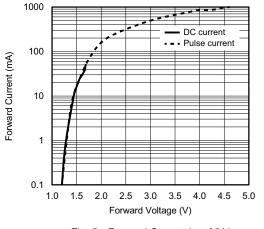


Fig. 5 - Forward Current  $I_F = f(V_F)$ 

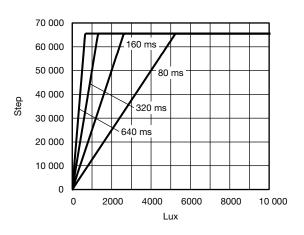


Fig. 6 - ALS Refresh Time vs. Maximum Detection Range

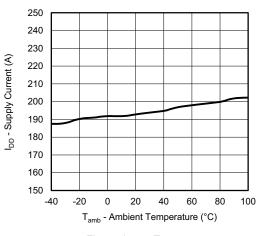


Fig. 7 -  $I_{\text{DD}}$  vs.Temperature

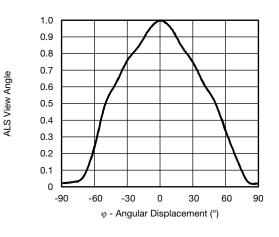
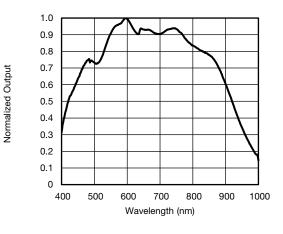


Fig. 8 - ALS View Angle





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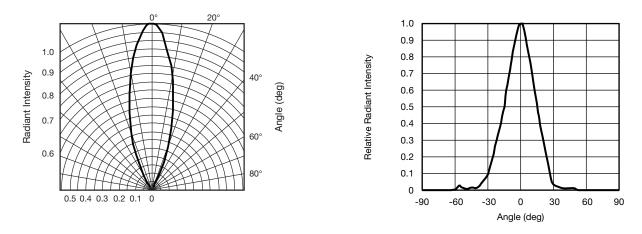


Fig. 10 - IRED Profile

### **APPLICATION INFORMATION**

#### Pin Connection with the Host

VCNL4040 integrates proximity sensor, ambient light Sensor, and IRED all together with I<sup>2</sup>C interface. It is very easy for the baseband (CPU) to access PS and ALS output data via I<sup>2</sup>C interface without extra software algorithms. The hardware schematic is shown in the following diagram.

Two additional capacitors in the circuit can be used for the following purposes: (1) the 0.1  $\mu$ F capacitor near the V<sub>DD</sub> pin is used for power supply noise rejection, (2) the 2.2  $\mu$ F capacitor - connected to the anode - is used to prevent the IRED voltage from instantly dropping when the IRED is turned on, and (3) 2.2 k $\Omega$  is suitable for the pull up resistor of I<sup>2</sup>C except for the 8.2 k $\Omega$  applied on the INT pin.

#### Note

• Cathode (LED) and cathode (sensor): pins need to be connected together externally

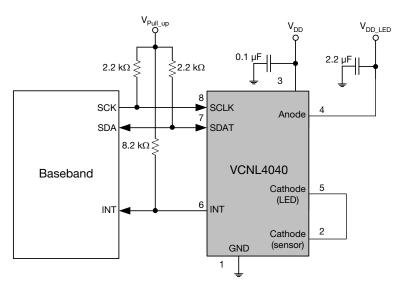


Fig. 11 - Hardware Pin Connection Diagram



### **Digital Interface**

VCNL4040 applies single slave address 0x60 (HEX) of 7-bit addressing following I<sup>2</sup>C protocol. As figure 12 shows, VCNL4040's I<sup>2</sup>C command format is simple for read and write operations between VCNL4040 and the host. The white sections indicate host activity and the gray sections indicate VCNL4040's acknowledgement of the host access activity. Write word and read word protocol is suitable for accessing registers particularly for 16-bit data ALS and 12-bit / 16-bit PS data. Interrupt can be cleared by reading data out from register: INT\_Flag. All command codes should follow read word and write word protocols.

Sen	d byte $\rightarrow$ write comn	nand	to \	/CNL4040													
1	7	1	1	8	1		8	1			8	1	1				
S	Slave address	Wr	А	Command code	А		Data byte low	А		Data	a byte high	А	Ρ				
Rec	Receive byte $\rightarrow$ read data from VCNL4040																
1	7	1	1	8	1	1	7		1	1	8			1	8	1	1
s	Slave address	Wr	А	Command code	А	s	Slave address		Rd	А	Data byte	low		А	Data byte high	Ν	Р
S = start condition   P = stop condition   A = acknowledge   N = not acknowledge																	

Fig. 12 - Write Word and Read Word Protocol

#### **Function Description**

VCNL4040 applies a 16-bit high resolution ALS that provides the best ambient light sensing capability down to 0.01 lux/step which works well under a low transmittance lens design (dark lens). A flexible interrupt function of ALS (register: ALS\_CONF) is also supported. The INT signal will not be triggered by VCNL4040 if the ALS value is not over high INT threshold window level, or lower than low INT threshold window level of ALS. VCNL4040 detects different light sources such as fluorescent light, incandescent light, sunlight, and white LED with high accuracy ALS data output after detecting algorithm is implemented.

For proximity sensor function, VCNL4040 supports different kinds of mechanical designs to achieve the best proximity detection performance for any color of object with more flexibility. The basic PS function settings, such as duty ratio, integration time, interrupt, and PS enable / disable, and persistence, are handled by the register: PS\_CONF1. Duty ratio controls the PS response time. Integration time represents the duration of the energy being received. The interrupt is triggered when the PS detection levels over the high threshold level setting (register: PS\_THDH) or lower than low threshold (register: PS\_THDL). If the interrupt function is enabled, the host can react to the interrupt pin, instead of polling the PS data registers. The INT flag (register: INT\_Flag) indicates the type of interrupt that has been triggered, depending on the interrupt settings in the configuration registers. PS persistence (PS\_PERS) sets up the PS INT trigger conditions, defining the amount of consecutive hits required before an interrupt event occurs. The intelligent cancellation level can be set on register: PS\_CANC to reduce the cross talk phenomenon.

VCNL4040 also supports an easy to use proximity detection logic mode, that triggers when the PS high threshold is exceeded and automatically resets the interrupt pin when the proximity reading falls beneath the PS low threshold. This functionality can be set in the register: PS\_MS. A smart persistence is provided to be able to prevent false PS interrupt trigger events. Descriptions of each of these parameters are shown in table 1.



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TABLE 1	- COMMA				ER DESCRIPTION
COMMAND CODE	DATE BYTE LOW / HIGH	REGISTER NAME	R / W	DEFAULT VALUE	FUNCTION DESCRIPTION
0x00	L	ALS_CONF	R/W	0x01	ALS integration time, persistence, interrupt, and function enable / disable
0,00	Н	Reserved	R / W	0x00	Reserved
0x01	L	ALS_THDH_L	R / W	0x00	ALS high interrupt threshold LSB byte
0.01	Н	ALS_THDH_M	R / W	0x00	ALS high interrupt threshold MSB byte
0x02	L	ALS_THDL_L	R / W	0x00	ALS low interrupt threshold LSB byte
0.02	Н	ALS_THDL_M	R / W	0x00	ALS low interrupt threshold MSB byte
0x03	L	PS_CONF1	R/W	0x01	PS duty ratio, integration time, persistence, and PS enable / disable
0x03	Н	PS_CONF2	R / W	0x00	PS output resolution selection, PS interrupt trigger method
	L	PS_CONF3	R/W	0x00	PS multi pulse, active force mode, sunlight immunity setting
0x04	н	PS_MS	R/W	0x00	White channel enable / disable, PS mode selection, PS protection setting, and LED current selection
0x05	L	PS_CANC_L	R/W	0x00	PS cancellation level setting
0.005	Н	PS_CANC_M	R/W	0x00	PS cancellation level setting
0x06	L	PS_THDL_L	R / W	0x00	PS low interrupt threshold setting LSB byte
0000	Н	PS_THDL_M	R / W	0x00	PS low interrupt threshold setting MSB byte
0x07	L	PS_THDH_L	R / W	0x00	PS high interrupt threshold setting LSB byte
0x07	Н	PS_THDH_M	R / W	0x00	PS high interrupt threshold setting MSB byte
0x08	L	PS_Data_L	R	0x00	PS LSB output data
0x06	Н	PS_Data_M	R	0x00	PS MSB output data
0x09	L	ALS_Data_L	R	0x00	ALS LSB output data
0x09	Н	ALS_Data_M	R	0x00	ALS MSB output data
0x0A	L	White_Data_L	R	0x00	White LSB output data
UXUA	Н	White_Data_M	R	0x00	White MSB output data
0x0B	L	Reserved	R	0x00	Reserved
UXUD	Н	INT_Flag	R	0x00	ALS, PS interrupt flags
0x0C	L	ID_L	R	0x86	Device ID LSB
0,00	Н	ID_M	R	0x01	Device ID MSB

### Note

• All of reserved register are used for internal test. Please keep as default setting.

### **Command Register Format**

VCNL4040 provides an 8-bit command register for ALS and PS controlling independently. The description of each command format is shown in following tables.

TABLE 2 - REGISTER: ALS_CONF DESCRIPTION													
REGISTER NAME		COMMAND CODE: 0x00_L (0x00 DATA BYTE LOW)											
Command	Bit	7	6	5	4	3	2	1	0				
REGISTER: ALS_C	ONF		COMMAND CODE: 0x00_L (0x00 DATA BYTE LOW)										
Command	Bit		Description										
ALS_IT	7:6		(0:0) = 80 ms; $(0:1) = 160$ ms; $(1:0) = 320$ ms; $(1:1) = 640$ ms ALS integration time setting, longer integration time has higher sensitivity										
Reserved	5:4	Default = (0	) : 0)										
ALS_PERS	3:2		(0 : 0) = 1, (0 : 1) = 2, (1 : 0) = 4, (1 : 1) = 8 ALS interrupt persistence setting										
ALS_INT_EN	1	0 = ALS int	0 = ALS interrupt disable, 1 = ALS interrupt enable										
ALS_SD	0	0 = ALS po	wer on, 1 = A	LS shut dowr	n, default = 1								



TABLE 3 - REGISTER: 00H_H DESCRIPTION									
REGISTER: Reser	ved	COMMAND CODE: 0x00_H (0x00 DATA BYTE HIGH)							
Command	Bit	Description							
Reserved	7:0	Default = (0 : 0 : 0 : 0 : 0 : 0 : 0 : 0)							

TABLE 4 - REGISTER ALS_THDH_L AND ALS_THDH_M DESCRIPTION								
COMMAND CODE: 0x01_L (0x01 DATA BYTE LOW) OR 0x01_H (0x01 DATA BYTE HIGH)								
Register	Bit	Description						
ALS_THDH_L	7:0	0x00 to 0xFF, ALS high interrupt threshold LSB byte						
ALS_THDH_M	7:0	0x00 to 0xFF, ALS high interrupt threshold MSB byte						

TABLE 5 - REGISTER: ALS_THDL_L AND ALS_THDL_M DESCRIPTION							
COMMAND CODE: 0x02_L (0x02 DATA BYTE LOW) AND 0x02_H(0x02 DATA BYTE HIGH)							
Register	Bit	Description					
ALS_THDL_L	7:0	0x00 to 0xFF, ALS low interrupt threshold LSB byte					
ALS_THDL_M	7:0	0x00 to 0xFF, ALS low interrupt threshold MSB byte					

TABLE 6 - REGISTER: PS_CONF1 DESCRIPTION							
REGISTER: PS_CO	ONF1	COMMAND CODE: 0x03_L (0x03 DATA BYTE LOW)					
Command	Bit	Description					
PS_Duty	7:6	(0 : 0) = 1/40, (0 : 1) = 1/80, (1 : 0) = 1/160, (1 : 1) = 1/320 PS IRED on / off duty ratio setting					
PS_PERS	5:4	(0 : 0) = 1, (0 : 1) = 2, (1 : 0) = 3, (1 : 1) = 4 PS interrupt persistence setting					
PS_IT	3 : 1	(0:0:0) = 1T, (0:0:1) = 1.5T, (0:1:0) = 2T, (0:1:1) = 2.5T, (1:0:0) = 3T, (1:0:1) = 3.5T, (1:1:0) = 4T, (1:1:1) = 8T, PS integration time setting					
PS_SD	0	0 = PS power on, 1 = PS shut down, default = 1					

TABLE 7 - REGISTER: PS_CONF2 DESCRIPTION						
REGISTER: PS_C	CONF2	COMMAND CODE: 0x03_H (0x03 DATA BYTE HIGH)				
Command	Bit	Description				
Reserved	7:6	(0 : 0), reserved				
Reserved	5:4	(0:0), reserved				
PS_HD	3	0 = PS output is 12 bits; 1 = PS output is 16 bits				
Reserved	2	Default = 0				
PS_INT	1:0	(0 : 0) = interrupt disable, (0 : 1) = trigger when close, (1 : 0)= trigger when away, (1 : 1)= trigger when close or away				

TABLE 8 - REGISTER: PS_CONF3 DESCRIPTION							
REGISTER: PS_CO	NF3	COMMAND CODE: 0x04_L (0x04 DATA BYTE LOW)					
Command	Bit	Description					
Reserved	7	0					
PS_MPS	6:5	Proximity multi pulse numbers (0 : 0) = 1, (0 : 1) = 2, (1 : 0) = 4, (1 : 1) = 8 multi pulses					
PS_SMART_PERS	4	) = disable; 1 = enable PS smart persistence					
PS_AF	3	= active force mode disable (normal mode), 1 = active force mode enable					
PS_TRIG	2	0 = no PS active force mode trigger, 1 = trigger one time cycle VCNL4040 output one cycle data every time host writes in '1' to sensor. The state returns to '0' automatically.					
Reserved	1	0					
PS_SC_EN	0	PS sunlight cancel enable setting, 1 = sunlight cancellation function enable					

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TABLE 9 - REGISTER: PS_MS DESCRIPTION							
REGISTER: PS_MS	S	COMMAND CODE: 0x04_H (0x04 DATA BYTE HIGH)					
Command	Bit	Description					
White_EN	7	0 = white channel enabled 1 = white channel disabled					
PS_MS	6	0 = proximity normal operation with interrupt function 1 = proximity detection logic output mode enable					
Reserved	5:3	(0:0:0)					
LED_I	2:0	(0 : 0 : 0) = 50 mA; (0 : 0 : 1) = 75 mA; (0 : 1 : 0) = 100 mA; (0 : 1 : 1) = 120 mA (1 : 0 : 0) = 140 mA; (1 : 0 : 1) = 160 mA; (1 : 1 : 0) = 180 mA; (1 : 1 : 1) = 200 mA LED current selection setting					

TABLE 10 - REGISTER PS_CANC_L AND PS_CANC_M DESCRIPTION								
COMMAND CODE: 0x05_L (0x05 DATA BYTE LOW) AND 0x05_H(0x05 DATA BYTE HIGH)								
Register	Bit	Description						
PS_CANC_L	PS_CANC_L 7:0 0x00 to 0xFF, PS cancellation level setting_LSB byte							
PS_CANC_M	7:0	0x00 to 0xFF, PS cancellation level setting_MSB byte						

TABLE 11 - REGISTER: PS_THDL_L AND PS_THDL_M DESCRIPTION							
COMMAND CODE: 0x06_L (0x06 DATA BYTE LOW) AND 0x06_H(0x06 DATA BYTE HIGH)							
Register	Bit	Description					
PS_THDL_L	7:0	0 0x00 to 0xFF, PS interrupt low threshold setting_LSB byte					
PS_THDL_M	7:0	0x00 to 0xFF, PS interrupt low threshold setting_MSB byte					

TABLE 12 - REGISTER: PS_THDH_L AND PS_THDH_M DESCRIPTION							
COMMAND CODE: 0x07_L (0x07 DATA BYTE LOW) AND 0x07_H(0x07 DATA BYTE HIGH)							
Register	Bit	Description					
PS_THDH_L	7:0	x00 to 0xFF, PS interrupt high threshold setting_LSB byte					
PS_THDH_M	7:0	0x00 to 0xFF, PS interrupt high threshold setting_MSB byte					

TABLE 13 - READ OUT REGISTER DESCRIPTION									
Register	Command Code	Bit	Description						
PS_Data_L	0x08_L (0x08 data byte low)	7:0	0x00 to 0xFF, PS LSB output data						
PS_Data_M	0x08_H (0x08 data byte high)	7:0	0x00 to 0xFF, PS MSB output data						
ALS_Data_L	0x09_L (0x09 data byte low)	7:0	0x00 to 0xFF, ALS LSB output data						
ALS_Data_M	0x09_H (0x09 data byte high)	7:0	0x00 to 0xFF, ALS MSB output data						
White_Data_L	0x0A_L (0x0A data byte low)	7:0	0x00 to 0xFF, white LSB output data						
White_Data_M	0x0A_H (0x0A data byte high)	7:0	0x00 to 0xFF, white LSB output data						
Reserved	0x0B_L (0x0B data byte low)	7:0	Default = 0x00						
INT_Flag	0x0B_H (0x0B data byte high)	7 6 5 4 3 2 1 0	Reserved PS_SPFLAG, PS entering protection mode ALS_IF_L, ALS crossing low THD INT trigger event ALS_IF_H, ALS crossing high THD INT trigger event Reserved Reserved PS_IF_CLOSE, PS rises above PS_THDH INT trigger event PS_IF_AWAY, PS drops below PS_THDL INT trigger event						
ID_L	0CH_L (0CH data byte low)	7:0	86H for MP version sample, device ID LSB byte						
ID_M	0CH_H (0CH data byte high)	7:6 5:4 3:0	(0 : 0) (0 : 0) Slave address = 0x60 (7-bit) Version code (0 : 0 : 0 : 1), device ID MSB byte						

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### Adjustable Sampling Time

VCNL4040's LED driver drives the internal IRED with the "LED CATHODE" pin by a pulsed duty cycle. The IRED on / off duty ratio can be set in register: PS\_Duty which is related to the current consumption and PS response time. The higher the duty ratio, the faster the response time achieved with higher power consumption. For example, PS\_Duty = 1/320, peak IRED current = 100 mA, averaged current consumption is 100 mA/320 = 0.3125 mA.

#### Initialization

VCNL4040 includes default values for each register. As long as power is on, it is ready to be controlled by host via I<sup>2</sup>C bus.

#### Threshold Window Setting

• ALS Threshold Window Setting (Applying ALS INT)

Register: ALS\_THDH\_L and ALS\_THDH\_M defines 16-bit ALS high threshold data for LSB byte and MSB byte. Register: ALS\_THDL\_L and ALS\_THDL\_M defines 16-bit ALS low threshold data for LSB byte and MSB byte. As long as ALS INT function is enabled, INT will be triggered once the ALS data exceeds ALS\_THDH or goes below ALS\_THDL. To easily define the threshold range, multiply the value of the resolution (lux/step) by the threshold level (refer to table 14).

TABLE 14 - ALS RESOLUTION AND MAXIMUM DETECTION RANGE									
	ALS_IT	SENSITIVITY	MAXIMUM DETECTION RANGE						
ALS_IT (7 : 6)	INTEGRATION TIME (typ.)	UNIT (lux/step)	UNIT (lux)						
(0, 0)	80 ms	0.10	6553.5						
(0, 1)	160 ms	0.05	3276.8						
(1, 0)	320 ms	0.025	1638.4						
(1, 1)	640 ms	0.0125	819.2						

ALS Persistence

The ALS INT is triggered once the ALS value is higher or lower than the threshold window. The ALS\_PERS (1, 2, 4, 8 times) parameter, sets the amount of consecutive hits needed, in order for an interrupt event to trigger.

Programmable PS Threshold

VCNL4040 provides both high and low thresholds setting for PS (register: PS\_THDL, PS\_THDH).

• PS Persistence

The PS persistence function (PS\_PERS, 1, 2, 3, 4) helps to avoid false trigger of the PS INT. It defines the amount of consecutive hits needed in order for a PS interrupt event to be triggered.

• PS Active Force mode

An extreme power saving way to use PS is to apply PS active force (register: PS\_CONF3 command: PS\_AF = 1) mode. Anytime host would like to request one proximity measurement, write a '1' into register: PS\_CONF3 command: PS\_Trig. This triggers a single PS measurement, which can be read from the PS result registers. VCNL4040 stays in standby mode constantly.

#### Data Access

All of VCNL4040 16 bit command registers are readable. The result data for ALS, white, and PS measurements can be read out form their respective registers. Each result is made of 2 bytes.

TABLE 15 - 16-BIT ALS DATA FORMAT																
		VCNL4040														
Bit	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Register				ALS_[	DataM							ALS_	DataL			

#### Intelligent Cancellation

VCNL4040 provides an intelligent cancellation method to reduce cross talk phenomenon for the proximity sensor. The output data will be subtracted by the value set in register: PS\_CANC.

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### Interruption (INT)

The VCNL4040 has an interrupt feature for both the PS and ALS channel. The purpose of the interrupt feature is to actively inform the host once INT has been triggered. When the interrupt is enabled, the host does not need to continuously read the data registers of the sensor, but instead can simply react to the interrupt pin. As long as the host enables ALS interrupt (register: ALS INT EN) or PS interrupt (register; PS INT) function, the level of INT pin (pin 6) is pulled low once an interrupt event has been triggered. All registers are accessible even if INT is triggered.

ALS INT is triggered when ALS value crosses over the value set in register: ALS\_THDH or below the value set by register: ALS\_THDL. PS INT is triggered when the PS value crosses over the value set in register: PS\_THDH or falls below the value set in register: PS\_THDL. Which of these thresholds to react to, can be set by the PS\_INT bits in the register: PS\_CONF2.

#### Interruption Flag

Register: INT Flag represents all of the interrupt trigger statuses for ALS and PS. If any of these flags trigger from "0" to "1", the INT pin will be pulled low. Once the host reads INT\_Flag register, all the flags are cleared (reset to "0"), and the INT pin is reset to high.

### PROXIMITY DETECTION LOGIC OUTPUT MODE

VCNL4040 has a proximity detection logic mode, enabling the host to read the state of PS (near or far) simply by monitoring the INT pin (pin 6). When this mode is selected, the INT pin is pulled low when an object is close to the sensor (value is above high threshold) and is reset to high when the object moves away (value is below low threshold). Register: PS\_THDH / PS\_THDL define where these threshold levels are set.

It should be noted that whenever the proximity detection logic mode has been enabled, the INT pin only reacts to proximity interrupt events. If the host would like to use ALS INT function, the bit PS MS in the register: PS MS needs to be set to normal operation mode (PS\_MS = 0). In order for the proximity detection logic mode to function, one of the PS\_INT bits in register: PS\_CONF2 must be enabled ("trigger when close", "trigger when away", or "trigger when close or away"). If PS\_INT is set to "INT Disable" the proximity detection logic mode will not function.

### **PROXIMITY DETECTION HYSTERESIS**

A hysteresis is created by setting the low and high threshold values. With proximity detection logic mode disabled, an interrupt event will trigger and stay triggered until it is cleared in the INT\_Flag register. The register is cleared automatically once it is read. If the interrupt flags are not cleared after an interrupt event has occurred, the VCNL4040 will not react to another interrupt event until the INT-Flag register has been cleared. An example of this could be when turning on and off a backlight of a mobile display. First the PS INT triggers when the PS value is over PS\_THDH. The host switches off the panel backlight and then clears INT. When PS value is less than PS\_THDL, host switches on panel backlight.

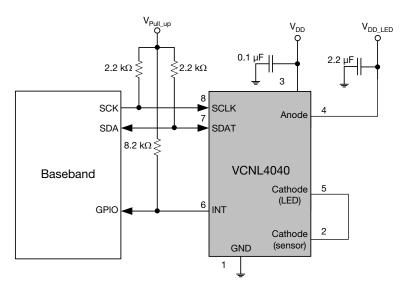


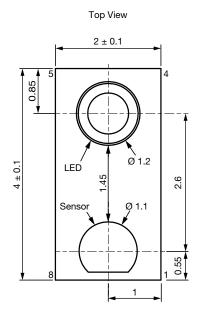
Fig. 13 - VCNL4040 Reference Circuit Connection with Host (Proximity Detection Logic Output Mode) (VCNL4040 INT pin connecting to BB GPIO instead of INT pin)

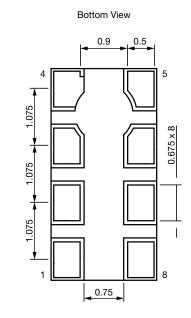


PACKAGE INFORMATION (VCNL4040M30E) in millimeters

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1	GND	5	Cathode (LED)
2	Cathode (sensor)	6	INT
3	V <sub>DD</sub>	7	SDAT
4	Anode	8	SCLK

Side View

 $1.1 \pm 0.05$ 

Fig. 14 - VCNL4040 Package Dimensions

## LAYOUT PAD INFORMATION (VCNL4040M30E) in millimeters

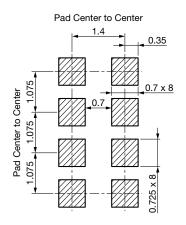


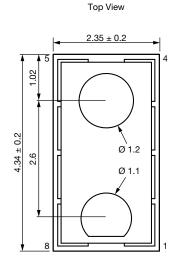
Fig. 15 - VCNL4040M3OE PCB Layout Footprint

Rev	18	28-Nov-2024
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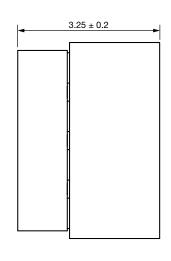
14

# PACKAGE INFORMATION (VCNL4040M30E-H3) in millimeters

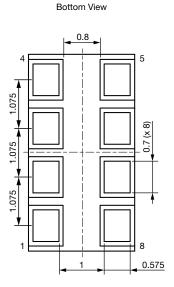
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Side View

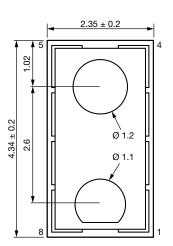


1	GND	5	Cathode (LED)
2	Cathode (sensor)	6	INT
3	V <sub>DD</sub>	7	SDAT
4	Anode	8	SCLK

Fig. 16 - VCNL4040M3OE-H3 Package Dimensions

### PACKAGE INFORMATION (VCNL4040M30E-H5) in millimeters

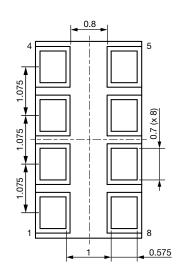
Top View



Side View

 $3.65 \pm 0.2$ 

Bottom View



1	GND	5	Cathode (LED)
2	Cathode (sensor)	6	INT
3	V <sub>DD</sub>	7	SDAT
4	Anode	8	SCLK

Fig. 17 - VCNL4040M3OE-H5 Package Dimensions



## LAYOUT PAD INFORMATION (VCNL4040M30E-H3, VCNL4040M30E-H5) in millimeters

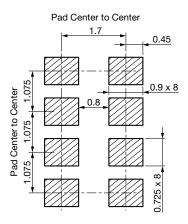


Fig. 18 - VCNL4040M3OE-H3 and H5 PCB Layout Footprint

## APPLICATION CIRCUIT BLOCK REFERENCE

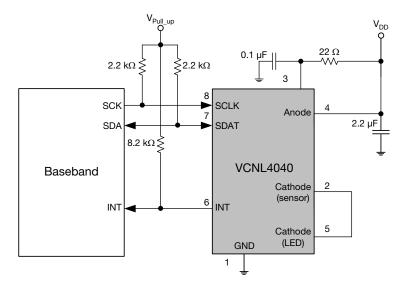


Fig. 19 - VCNL4040 Application Circuit (V<sub>DD</sub> (sensor and LED) suggestion circuit)



RECOMMENDED STORAGE AND REBAKING CONDITIONS				
PARAMETER	CONDITIONS	MIN.	MAX.	UNIT
Storage temperature		5	50	°C
Relative humidity			60	%
Open time			168	h
Total time	From the date code on the aluminized envelope (unopened)		12	months
Rebaking	Tape and Reel: 60 °C		22	h
	Tube: 60 °C		22	h

### **RECOMMENDED INFRARED REFLOW**

Soldering conditions which are based on J-STD-020 C

IR REFLOW PROFILE CONDITION				
PARAMETER	CONDITIONS	TEMPERATURE	TIME	
Peak temperature		260 °C + 5 °C / - 5 °C (max.: 265 °C)	10 s	
Preheat temperature range and timing		150 °C to 200 °C	60 s to 180 s	
Timing within 5 °C to peak temperature			10 s to 30 s	
Timing maintained above temperature / time		217 °C	60 s to 150 s	
Timing from 25 °C to peak temperature			8 minutes (max.)	
Ramp-up rate		3 °C/s (max.)		
Ramp-down rate		6 °C/s (max.)		

Recommend Normal Solder Reflow is 235 °C to 265 °C

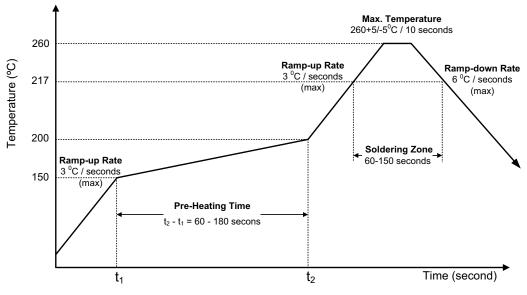


Fig. 20 - VCNL4040 Solder Reflow Profile Chart

# **VCNL4040**

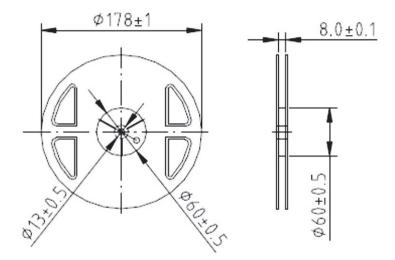
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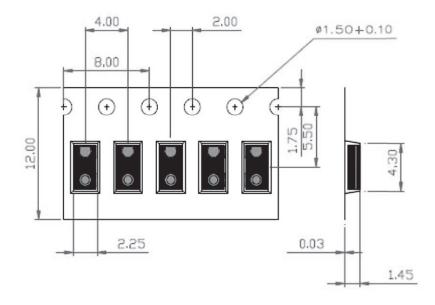
**Vishay Semiconductors** 

## **RECOMMENDED IRON TIP SOLDERING CONDITION AND WARNING HANDLING**

- 1. Solder the device with the following conditions:
  - 1.1.Soldering temperature: 400 °C (max.)
  - 1.2.Soldering time: 3 s (max.)
- 2. If the temperature of the method portion rises in addition to the residual stress between the leads, the possibility that an open or short circuit occurs due to the deformation or destruction of the resin increases.
- 3. The following methods: VPS and wave soldering, have not been suggested for the component assembly.
- 4. Cleaning method conditions:
  - 4.1. Solvent: methyl alcohol, ethyl alcohol, isopropyl alcohol
  - 4.2.Solvent temperature < 45 °C (max.)
  - 4.3.Time: 3 minutes (min.)

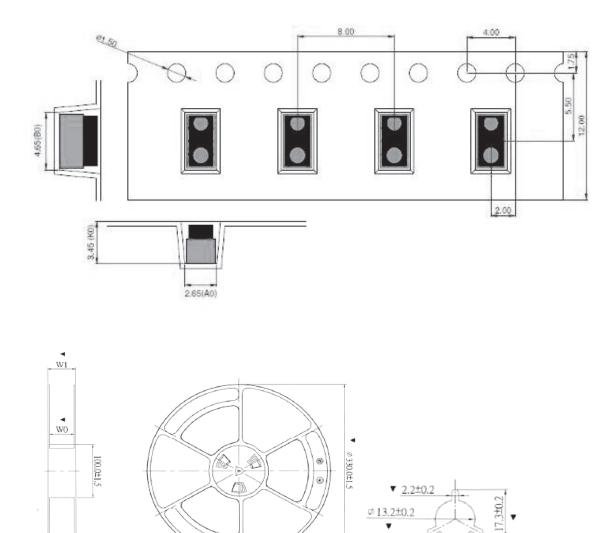
### TAPE PACKAGING INFORMATION in millimeters







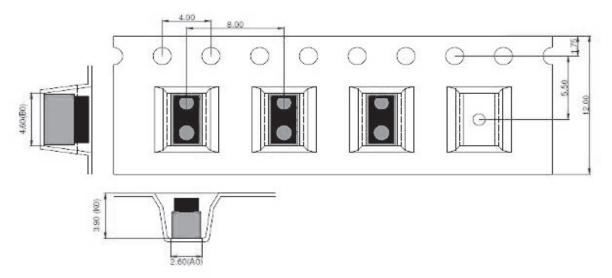
## TAPE PACKAGING INFORMATION (VCNL4040M30E-H3) in millimeters

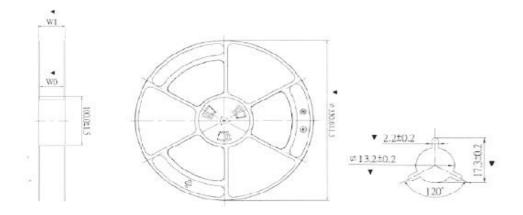


W0: 12.6 +/- 0.5 mm W1: 20.6 +/- 0.5mm Tolerance:±0.1(unit=mm) Quantity:1500pcs/Ree1 120



## TAPE PACKAGING INFORMATION (VCNL4040M30E-H5) in millimeters





W0:12.6+/-0.5 mm W1:20.6+/-0.5mm Tolerance:±0.1(unit=mm) Quantity:1500pcs/Reel



# Footprint and Schematic Information for VCNL4040

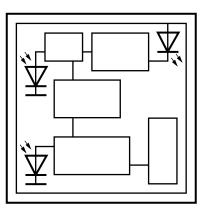
The footprint and schematic symbols for the following parts can be accessed using the link to the SnapEDA website. They are available in Eagle, Altium, KiCad, OrCAD / Allegro, Pulsonix, and PADS.

Note that the 3D models for these parts can be found on the Vishay product page. The links are included here for convenience.

PART NUMBER FOOTPRINT / SCHEMATIC		3D MODEL	
VCNL4040-M30E-H3	www.snapeda.com/parts/VCNL4040M3OE-H3/Vishay/view-part/	-	
VCNL4040-M30E-H5	www.snapeda.com/parts/VCNL4040M3OE-H5/Vishay/view-part/	-	
VCNL4040-M30E	www.snapeda.com/parts/VCNL4040M3OE/Vishay/view-part/	www.vishay.com/doc?84352	

For technical issues and product support, please contact sensorstechsupport@vishay.com.







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