



# SN65MLVD201, SN65MLVD203 SN65MLVD206, SN65MLVD207

SLLS558C-DECEMBER 2002-REVISED JANUARY 2007

# MULTIPOINT-LVDS LINE DRIVER AND RECEIVER

#### **FEATURES**

- Low-Voltage Differential 30-Ω to 55-Ω Line Drivers and Receivers for Signaling Rates<sup>(1)</sup> Up to 200 Mbps
- Type-1 Receivers Incorporate 25 mV of Hysteresis
- Type-2 Receivers Provide an Offset (100 mV)
   Threshold to Detect Open-Circuit and Idle-Bus Conditions
- Meets or Exceeds the M-LVDS Standard TIA/EIA-899 for Multipoint Data Interchange
- Controlled Driver Output Voltage Transition
   Times for Improved Signal Quality
- -1 V to 3.4 V Common-Mode Voltage Range Allows Data Transfer With 2 V of Ground Noise
- Bus Pins High Impedance When Disabled or  $V_{CC} \le 1.5 \text{ V}$
- 100-Mbps Devices Available (SN65MLVD200A, 202A, 204A, 205A)
- M-LVDS Bus Power Up/Down Glitch Free

The signaling rate of a line, is the number of voltage transitions that are made per second expressed in the units bps (bits per second).

#### **APPLICATIONS**

- Low-Power High-Speed Short-Reach Alternative to TIA/EIA-485
- Backplane or Cabled Multipoint Data and Clock Transmission
- Cellular Base Stations
- Central-Office Switches
- Network Switches and Routers

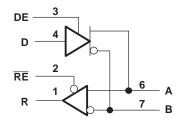
### DESCRIPTION

The SN65MLVD201, 203, 206, and 207 are multipoint-low-voltage differential (M-LVDS) line drivers and receivers, which are optimized to operate at signaling rates up to 200 Mbps. All parts comply with the multipoint low-voltage differential signaling (M-LVDS) standard TIA/EIA-899. These circuits are similar to their TIA/EIA-644 standard compliant LVDS counterparts, with added features to address multipoint applications. The driver output has been designed to support multipoint buses presenting loads as low as 30  $\Omega$ , and incorporates controlled transition times to allow for stubs off of the backbone transmission line.

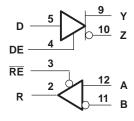
These devices have Type-1 and Type-2 receivers that detect the bus state with as little as 50 mV of differential input voltage over a common-mode voltage range of -1 V to 3.4 V. The Type-1 receivers exhibit 25 mV of differential input voltage hysteresis to prevent output oscillations with slowly changing signals or loss of input. Type-2 receivers include an offset threshold to provide a known output state under open-circuit, idle-bus, and other faults conditions. The devices are characterized for operation from -40°C to 85°C.

# **LOGIC DIAGRAM (POSITIVE LOGIC)**

SN65MLVD201, SN65MLVD206



### SN65MLVD203, SN65MLVD207





Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.

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These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

#### **ORDERING INFORMATION**

PART NUMBER (1)	FOOTPRINT	RECEIVER TYPE	PACKAGE MARKING
SN65MLVD201D	SN75176	Type 1	MF201
SM65MLVD203D	SN75ALS180	Type 1	MLVD203
SN65MLVD206D	SN75176	Type 2	MF206
SM65MLVD207D	SN75ALS180	Type 2	MLVD207

<sup>(1)</sup> For the most current package and ordering information, see the Package Option Addendum at the end of this document, or see the TI website at www.ti.com.

#### PACKAGE DISSIPATION RATINGS

PACKAGE	T <sub>A</sub> ≤ 25°C POWER RATING	DERATING FACTOR ABOVE T <sub>A</sub> = 25°C	T <sub>A</sub> = 85°C POWER RATING
D(8)	725 mW	5.8 mW/°C	377 mW
D(14)	950 mW	7.6 mW/°C	494 mw

### **ABSOLUTE MAXIMUM RATINGS**

over operating free-air temperature range (unless otherwise noted) (1)

			VALUE / UNIT
Supply voltage range (2),	V <sub>CC</sub>		–0.5 V to 4 V
	D, DE, RE		−0.5 V to 4 V
Input voltage range	A, B (201, 206)		–1.8 V to 4 V
	A, B (203, 207)	–4 V to 6 V	
R R			–0.3 V to 4 V
Output voltage range	Y, Z, A, or B		–1.8 V to 4 V
	Human Body Model (3)	A, B, Y, and Z	±8 kV
Electrostatic discharge	numan body woder	All pins	±2 kV
	Charged-Device Model (4)	Charged-Device Model <sup>(4)</sup> All pins	
Continuous power dissipation			See Dissipation Rating Table
Storage temperature ran	ge		−65°C to 150°C

<sup>(1)</sup> Stresses beyond those listed under absolute maximum ratings may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under recommended operating conditions is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

#### RECOMMENDED OPERATING CONDITIONS

		MIN	NOM	MAX	UNIT
$V_{CC}$	Supply voltage	3	3.3	3.6	V
V <sub>IH</sub>	High-level input voltage	2		V <sub>CC</sub>	V
V <sub>IL</sub>	Low-level input voltage	GND		0.8	V
	Voltage at any bus terminal V <sub>A</sub> , V <sub>B</sub> , V <sub>Y</sub> or V <sub>Z</sub>	-1.4		3.8	V
$ V_{ID} $	Magnitude of differential input voltage	0.05		V <sub>CC</sub>	V
$T_A$	Operating free-air temperature	-40		85	°C

All voltage values, except differential I/O bus voltages, are with respect to network ground terminal.

Tested in accordance with JEDEC Standard 22, Test Method A114-A. Tested in accordance with JEDEC Standard 22, Test Method C101.



### **DEVICE ELECTRICAL CHARACTERISTICS**

over recommended operating conditions (unless otherwise noted)

	PARAMETER		TEST CONDITIONS	MIN TYP <sup>(1)</sup>	MAX	UNIT
Driver only R		Driver only	$\overline{\text{RE}}$ and DE at V <sub>CC</sub> , R <sub>L</sub> = 50 $\Omega$ , All others open	13	22	
		Both disabled	$\overline{RE}$ at $V_{CC}$ , DE at 0 V, $R_L$ = No Load, All others open	1	4	mA
ICC	Supply current	Both enabled	$\overline{\text{RE}}$ at 0 V, DE at V <sub>CC</sub> , R <sub>L</sub> = 50 $\Omega$ , All others open	16	24	ША
		Receiver only	$\overline{\text{RE}}$ at 0 V, DE at 0 V, R <sub>L</sub> = 50 $\Omega$ , All others open	4	13	

<sup>(1)</sup> All typical values are at 25°C and with a 3.3-V supply voltage.

### **DRIVER ELECTRICAL CHARACTERISTICS**

over recommended operating conditions (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN <sup>(1)</sup>	TYP <sup>(2)</sup> MAX	UNIT
$ V_{AB} $ or $ V_{YZ} $	Differential output voltage magnitude	See Figure 2	480	650	mV
$\Delta  V_{AB} $ or $\Delta  V_{YZ} $	Change in differential output voltage magnitude between logic states	See Figure 2	-50	50	mV
V <sub>OS(SS)</sub>	Steady-state common-mode output voltage		0.8	1.2	V
$\Delta V_{OS(SS)}$	Change in steady-state common-mode output voltage between logic states	See Figure 3	-50	50	mV
V <sub>OS(PP)</sub>	Peak-to-peak common-mode output voltage			150	mV
$V_{Y(OC)}$ or $V_{A(OC)}$	Maximum steady-state open-circuit output voltage	See Figure 7	0	2.4	٧
$V_{Z(OC)}$ or $V_{B(OC)}$	Maximum steady-state open-circuit output voltage	See Figure 7	0	2.4	٧
$V_{P(H)}$	Voltage overshoot, low-to-high level output	See Figure 5		1.2 V <sub>SS</sub>	V
$V_{P(L)}$	Voltage overshoot, high-to-low level output	See Figure 5	-0.2 V <sub>SS</sub>		<b>V</b>
I <sub>IH</sub>	High-level input current (D, DE)	V <sub>IH</sub> = 2 V	0	10	μΑ
I <sub>IL</sub>	Low-level input current (D, DE)	$V_{IL} = 0.8 \ V$	0	10	μΑ
$JI_{OS}J$	Differential short-circuit output current magnitude	See Figure 4		24	mA
I <sub>OZ</sub>	High-impedance state output current (driver only)	$-1.4 \text{ V} \le \text{V}_{\text{Y}} \text{ or } \text{V}_{\text{Z}} \le 3.8 \text{ V},$ Other output = 1.2 V	-15	10	μΑ
I <sub>O(OFF)</sub>	Power-off output current	$-1.4 \text{ V} \leq \text{V}_{\text{Y}} \text{ or } \text{V}_{\text{Z}} \leq 3.8 \text{ V},$ Other output = 1.2 V, $0 \text{ V} \leq \text{V}_{\text{CC}} \leq 1.5 \text{ V}$	-10	10	μΑ
C <sub>Y</sub> or C <sub>Z</sub>	Output capacitance	$V_I = 0.4 \sin(30E6\pi t) + 0.5 \text{ V}, ^{(3)}$ Other input at 1.2 V, Driver disabled		3	pF
$C_{YZ}$	Differential output capacitance	$V_{AB} = 0.4 \sin(30E6\pi t) \text{ V, }^{(3)}$ Driver disabled		2.5	pF
C <sub>Y/Z</sub>	Output capacitance balance, $(C_Y/C_Z)$		0.99	1.01	

<sup>(1)</sup> The algebraic convention, in which the least positive (most negative) limit is designated as minimum is used in this data sheet.

<sup>(2)</sup> All typical values are at 25°C and with a 3.3-V supply voltage.

<sup>3)</sup> HP4194A impedance analyzer (or equivalent)

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# RECEIVER ELECTRICAL CHARACTERISTICS

over recommended operating conditions unless otherwise noted (1)

	PARAMETER		TEST CONDITIONS	MIN	TYP <sup>(1)</sup>	MAX	UNIT
V	Desitive going differential input voltage threshold	Type 1				50	m)/
V <sub>IT+</sub>	Positive-going differential input voltage threshold	Type 2				150	mV
V	Negative going differential input voltage threshold	Type 1	See Figure 9 and Table 1 and	-50			m\/
V <sub>IT-</sub>	Negative-going differential input voltage threshold	Type 2	Table 2	50			mV
V	Differential input valters by starce is ()/		25		mV		
V <sub>HYS</sub>	Differential input voltage hysteresis, $(V_{IT+} - V_{IT})$	Type 2			0		IIIV
V <sub>OH</sub>	High-level output voltage		$I_{OH} = -8 \text{ mA}$	2.4			V
V <sub>OL</sub>	Low-level output voltage		I <sub>OL</sub> = 8 mA			0.4	V
I <sub>IH</sub>	High-level input current (RE)		V <sub>IH</sub> = 2 V	-10		0	μΑ
I <sub>IL</sub>	Low-level input current (RE)		V <sub>IL</sub> = 0.8 V	-10		0	μΑ
I <sub>OZ</sub>	High-impedance output current		V <sub>O</sub> = 0 V or 3.6 V	-10		15	μΑ
C <sub>A</sub> or C <sub>B</sub>	A or C <sub>B</sub> Input capacitance		V <sub>I</sub> = 0.4 sin(30E6πt) + 0.5 V, <sup>(2)</sup> Other input at 1.2 V		3		pF
C <sub>AB</sub>	Differential input capacitance		$V_{AB} = 0.4 \sin(30E6\pi t) V^{(2)}$			2.5	pF
C <sub>A/B</sub>	Input capacitance balance, (C <sub>A</sub> /C <sub>B</sub> )			0.99		1.01	

 <sup>(1)</sup> All typical values are at 25°C and with a 3.3-V supply voltage.
 (2) HP4194A impedance analyzer (or equivalent)



#### **BUS INPUT AND OUTPUT ELECTRICAL CHARACTERISTICS**

over recommended operating conditions (unless otherwise noted)

	PARAMETER	Ti	EST CONDITIO	NS	MIN	TYP <sup>(1)</sup>	MAX	UNIT
		V <sub>A</sub> = 3.8 V,	V <sub>B</sub> = 1.2 V,		0		32	
I <sub>A</sub>	Receiver or transceiver with driver disabled input current	$V_A = 0 \text{ V or } 2.4 \text{ V}, \qquad V_B = 1.2 \text{ V}$			-20		20	μΑ
	albabica input carrent	$V_A = -1.4 \text{ V},$	V <sub>B</sub> = 1.2 V		-32		0	
		$V_B = 3.8 V$ ,	V <sub>A</sub> = 1.2 V		0		32	
I <sub>B</sub>	Receiver or transceiver with driver disabled input current	$V_B = 0 \text{ V or } 2.4 \text{ V},$	V <sub>A</sub> = 1.2 V		-20		20	μΑ
	disabled input durient	$V_B = -1.4 V$ ,	V <sub>A</sub> = 1.2 V		-32		0	
I <sub>AB</sub>	Receiver or transceiver with driver disabled differential input current $(I_A - I_B)$	$V_A = V_B$	1.4 ≤ V <sub>A</sub> ≤ 3.8	3 V	-4		4	μΑ
		$V_A = 3.8 V$ ,	$V_B = 1.2 V,$	$0 \text{ V} \leq \text{V}_{\text{CC}} \leq 1.5 \text{ V}$	0		32	
I <sub>A(OFF)</sub>	Receiver or transceiver power-off input current	$V_A = 0 \text{ V or } 2.4 \text{ V},$	$V_B = 1.2 V,$	0 V ≤ V <sub>CC</sub> ≤ 1.5 V	-20		20	μΑ
	input current	$V_A = -1.4 V$ ,	V <sub>B</sub> = 1.2 V,	0 V ≤ V <sub>CC</sub> ≤ 1.5 V	-32		0	
		$V_B = 3.8 V$ ,	V <sub>A</sub> = 1.2 V,	0 V ≤ V <sub>CC</sub> ≤ 1.5 V	0		32	
I <sub>B(OFF)</sub>	Receiver or transceiver power-off input current	$V_B = 0 \text{ V or } 2.4 \text{ V},$	V <sub>A</sub> = 1.2 V,	0 V ≤ V <sub>CC</sub> ≤ 1.5 V	-20		20	μΑ
	input durient	$V_B = -1.4 V$ ,	V <sub>A</sub> = 1.2 V,	0 V ≤ V <sub>CC</sub> ≤ 1.5 V	-32		0	
I <sub>AB(OFF)</sub>	Receiver input or transceiver power-off differential input current $(I_A - I_B)$	$V_A = V_B$ , $0 \text{ V} \le V_{CC}$	≤ 1.5 V, –1.4 ≤	V <sub>A</sub> ≤ 3.8 V	-4		4	μΑ
C <sub>A</sub>	Transceiver with driver disabled input capacitance	$V_A = 0.4 \sin (30E6\pi)$	t) + 0.5V <sup>(2)</sup> ,	V <sub>B</sub> = 1.2 V		5		pF
Св	Transceiver with driver disabled input capacitance	$V_B = 0.4 \sin (30E6\pi)$	t) + 0.5 V <sup>(2)</sup> ,	V <sub>A</sub> = 1.2 V		5		pF
C <sub>AB</sub>	Transceiver with driver disabled differential input capacitance	V <sub>AB</sub> = 0.4 sin (30E6	πt)V <sup>(2)</sup>				3	pF
C <sub>A/B</sub>	Transceiver with driver disabled input capacitance balance, (C <sub>A</sub> /C <sub>B</sub> )				0.99		1.01	

<sup>(1)</sup> All typical values are at 25°C and with a 3.3-V supply voltage.

#### DRIVER SWITCHING CHARACTERISTICS

over recommended operating conditions (unless otherwise noted)

PARAM	IETER	TEST CONDITIONS	MIN	TYP <sup>(1)</sup>	MAX	UNIT
t <sub>PLH</sub>	Propagation delay time, low-to-high-level output		1	1.5	2.4	ns
t <sub>PHL</sub>	Propagation delay time, high-to-low-level output		1	1.5	2.4	ns
t <sub>r</sub>	Differential output signal rise time	Con Figure 5	1		1.6	ns
t <sub>f</sub>	Differential output signal fall time	See Figure 5	1		1.6	ns
t <sub>sk(p)</sub>	Pulse skew ( t <sub>PHL</sub> - t <sub>PLH</sub>  )			0	100	ps
t <sub>sk(pp)</sub>	Part-to-part skew <sup>(2)</sup>				1	ns
t <sub>jit(per)</sub>	Period jitter, rms (1 standard deviation) <sup>(3)</sup>	100 MHz clock input <sup>(4)</sup>		2	3	ps
t <sub>jit(pp)</sub>	Peak-to-peak jitter <sup>(3) (5)</sup>	200 Mbps 2 <sup>15</sup> –1 PRBS input <sup>(6)</sup>		30	130	ps
t <sub>PHZ</sub>	Disable time, high-level-to-high-impedance output				7	ns
t <sub>PLZ</sub>	Disable time, low-level-to-high-impedance output	Con Figure C			7	ns
t <sub>PZH</sub>	Enable time, high-impedance-to-high-level output	See Figure 6			7	ns
t <sub>PZL</sub>	Enable time, high-impedance-to-low-level output				7	ns

<sup>(1)</sup> All typical values are at 25°C and with a 3.3-V supply voltage.

<sup>(2)</sup> HP4194A impedance analyzer (or equivalent)

<sup>(2)</sup>  $t_{sk(pp)}$  is the magnitude of the time difference in propagation delay times between any specified terminals of two devices when both devices operate with the same supply voltages, at the same temperature, and have identical packages and test circuits.

<sup>(3)</sup> Jitter is ensured by design and characterization. Stimulus jitter has been subtracted from the numbers.

<sup>4)</sup>  $t_r = t_f = 0.5 \text{ ns } (10\% \text{ to } 90\%), \text{ measured over } 30 \text{ k samples.}$ 

<sup>(5)</sup> Peak-to-peak jitter includes jitter due to pulse skew (t<sub>sk(p)</sub>).

<sup>6)</sup>  $t_r = t_f = 0.5 \text{ ns } (10\% \text{ to } 90\%), \text{ measured over } 100 \text{ k samples.}$ 

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#### RECEIVER SWITCHING CHARACTERISTICS

over recommended operating conditions (unless otherwise noted)

	PARAMETER		TEST CONDITIONS	MIN	TYP <sup>(1)</sup>	MAX	UNIT
t <sub>pLH</sub>	Propagation delay time, low-to-high-level output			2	4	6	ns
t <sub>pHL</sub>	Propagation delay time, high-to-low-level output			2	4	6	ns
t <sub>r</sub>	Output signal rise time			1		2.3	ns
t <sub>f</sub>	Output signal fall time		C <sub>L</sub> = 15 pF, See Figure 10	1		2.3	ns
	Pulso akow (lt t l)	Type 1			100	300	ps
t <sub>sk(p)</sub>	Pulse skew ( $ t_{pHL} - t_{pLH} $ )	Type 2			300	500	ps
t <sub>sk(pp)</sub>	Part-to-part skew <sup>(2)</sup>					1	ns
t <sub>jit(per)</sub>	Period jitter, rms (1 standard deviation) (3)		100 MHz clock input <sup>(4)</sup>		4	7	ps
	Peak to peak iittor(3)(5)	Type 1	200 Mbps 2 <sup>15</sup> –1 PRBS input <sup>(6)</sup>		300	700	ps
t <sub>jit(pp)</sub>	Peak-to-peak jitter(3)(5)	Type 2		450	800	ps	
t <sub>pHZ</sub>	Disable time, high-level-to-high-impedance output					10	ns
t <sub>pLZ</sub>	Disable time, low-level-to-high-impedance output		See Figure 44			10	ns
t <sub>pZH</sub>	Enable time, high-impedance-to-high-level output		See Figure 11			15	ns
t <sub>pZL</sub>	Enable time, high-impedance-to-low-level output					15	ns

All typical values are at 25°C and with a 3.3-V supply voltage.

t<sub>sk(pp)</sub> is the magnitude of the time difference in propagation delay times between any specified terminals of two devices when both devices operate with the same supply voltages, at the same temperature, and have identical packages and test circuits. Jitter is ensured by design and characterization. Stimulus jitter has been subtracted from the numbers.  $V_{ID} = 200 \text{ mV}_{pp}$  (LVD201, 203),  $V_{ID} = 400 \text{ mV}_{pp}$  (LVD206, 207),  $V_{cm} = 1 \text{ V}$ ,  $V_{r} = t_f = 0.5 \text{ ns}$  (10% to 90%), measured over 30 k samples.

Peak-to-peak jitter includes jitter due to pulse skew ( $t_{sk(p)}$ ).  $V_{ID} = 200 \text{ mV}_{pp}$  (LVD201, 203),  $V_{ID} = 400 \text{ mV}_{pp}$  (LVD206, 207),  $V_{cm} = 1 \text{ V}$ ,  $t_r = t_f = 0.5 \text{ ns}$  (10% to 90%), measured over 100 k samples.



#### PARAMETER MEASUREMENT INFORMATION

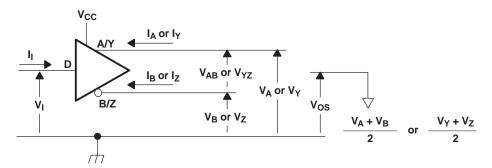
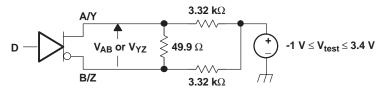
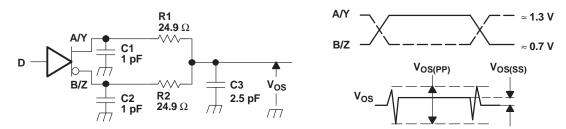


Figure 1. Driver Voltage and Current Definitions



All resistors are 1% tolerance.

Figure 2. Differential Output Voltage Test Circuit



- A. All input pulses are supplied by a generator having the following characteristics: t<sub>r</sub> or t<sub>f</sub>≤ 1 ns, pulse frequency = 500 kHz, duty cycle = 50 ± 5%.
- B. C1, C2 and C3 include instrumentation and fixture capacitance within 2 cm of the D.U.T. and are 20%.
- C. R1 and R2 are metal film, surface mount, 1%, and located within 2 cm of the D.U.T.
- D. The measurement of V<sub>OS(PP)</sub> is made on test equipment with a -3 dB bandwidth of at least 1 GHz.

Figure 3. Test Circuit and Definitions for the Driver Common-Mode Output Voltage

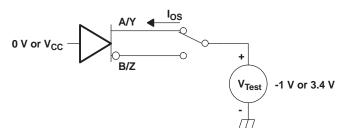
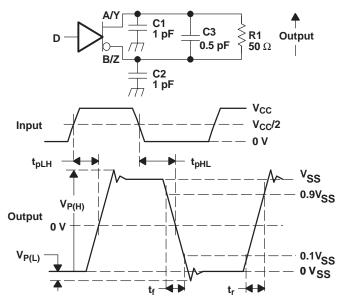


Figure 4. Driver Short-Circuit Test Circuit

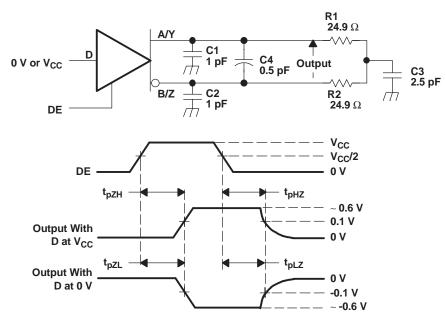


# PARAMETER MEASUREMENT INFORMATION (continued)



- A. All input pulses are supplied by a generator having the following characteristics: t<sub>r</sub> or t<sub>f</sub>≤ 1 ns, frequency = 500 kHz, duty cycle = 50 5%.
- B. C1, C2, and C3 include instrumentation and fixture capacitance within 2 cm of the D.U.T. and are 20%.
- C. R1 is a metal film, surface mount, and 1% tolerance and located within 2 cm of the D.U.T.
- D. The measurement is made on test equipment with a -3 dB bandwidth of at least 1 GHz.

Figure 5. Driver Test Circuit, Timing, and Voltage Definitions for the Differential Output Signal



- A. All input pulses are supplied by a generator having the following characteristics: t<sub>r</sub> or t<sub>f</sub>≤ 1 ns, frequency = 500 kHz, duty cycle = 50 5%.
- B. C1, C2, C3, and C4 includes instrumentation and fixture capacitance within 2 cm of the D.U.T. and are 20%.
- C. R1 and R2 are metal film, surface mount, and 1% tolerance and located within 2 cm of the D.U.T.
- D. The measurement is made on test equipment with a -3 dB bandwidth of at least 1 GHz.

Figure 6. Driver Enable and Disable Time Circuit and Definitions



# PARAMETER MEASUREMENT INFORMATION (continued)

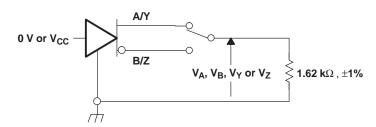
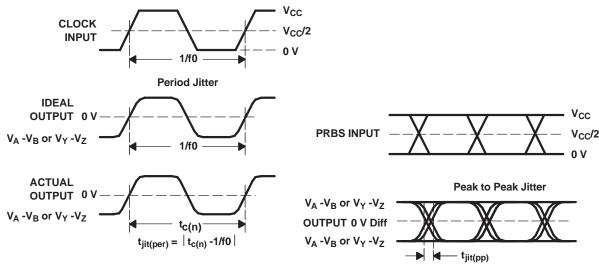


Figure 7. Maximum Steady State Output Voltage



- A. All input pulses are supplied by an Agilent 8304A Stimulus System.
- B. The measurement is made on a TEK TDS6604 running TDSJIT3 application software
- C. Period jitter is measured using a 100 MHz 50 1% duty cycle clock input.
- D. Peak-to-peak jitter is measured using a 200Mbps 2<sup>15</sup>-1 PRBS input.

Figure 8. Driver Jitter Measurement Waveforms

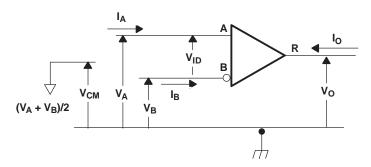


Figure 9. Receiver Voltage and Current Definitions



Table 1. Type-1 Receiver Input Threshold Test Voltages

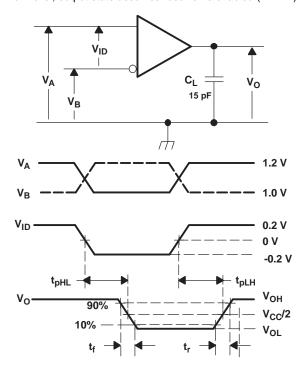
	LIED AGES	RESULTING DIFFERENTIAL INPUT VOLTAGE	RESULTING COMMON- MODE INPUT VOLTAGE	RECEIVER OUTPUT <sup>(1)</sup>
VIA	$V_{IB}$	$V_{ID}$	V <sub>IC</sub>	OUIFUI
2.400	0.000	2.400	1.200	Н
0.000	2.400	-2.400	1.200	L
3.800	3.750	0.050	3.775	Н
3.750	3.800	-0.050	3.775	L
-1.350	-1.400	0.050	-1.375	Н
-1.400	-1.350	-0.050	-1.375	L

(1) H = high level, L = low level, output state assumes receiver is enabled ( $\overline{RE} = L$ )

Table 2. Type-2 Receiver Input Threshold Test Voltages

1	LIED AGES	RESULTING DIFFERENTIAL INPUT VOLTAGE	INPUT VOLTAGE MODE INPUT VOLTAGE	
V <sub>IA</sub>	V <sub>IB</sub>	$V_{ID}$	V <sub>IC</sub>	OUTPUT <sup>(1)</sup>
2.400	0.000	2.400	1.200	Н
0.000	2.400	-2.400	1.200	L
3.800	3.650	0.150	3.725	Н
3.800	3.750	0.050	3.775	L
-1.250	-1.400	0.150	-1.325	Н
-1.350	-1.400	0.050	-1.375	L

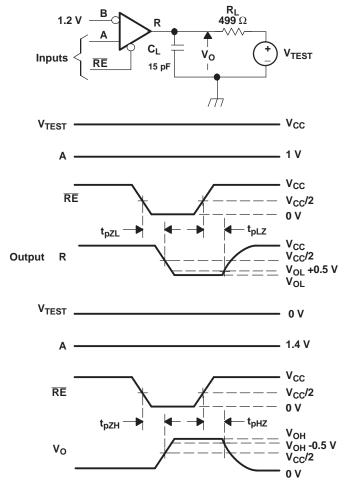
(1) H = high level, L = low level, output state assumes receiver is enabled ( $\overline{RE} = L$ )



- A. All input pulses are supplied by a generator having the following characteristics:  $t_r$  or  $t_f \le 1$  ns, frequency = 50 MHz, duty cycle = 50 5%.  $C_L$  is a combination of a 20%-tolerance, low-loss ceramic, surface-mount capacitor and fixture capacitance within 2 cm of the D.U.T.
- B. The measurement is made on test equipment with a –3 dB bandwidth of at least 1 GHz.

Figure 10. Receiver Timing Test Circuit and Waveforms

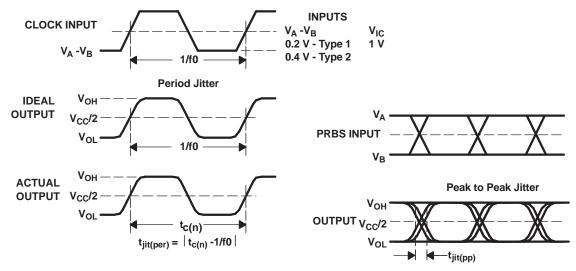




- A. All input pulses are supplied by a generator having the following characteristics: t<sub>r</sub> or t<sub>f</sub>≤ 1 ns, frequency = 500 kHz, duty cycle = 50 5%.
- B. R<sub>L</sub> is 1% tolerance, metal film, surface mount, and located within 2 cm of the D.U.T.
- C. R<sub>L</sub> is 1% tolerance, metal film, surface mount, and located within 2 cm of the D.U.T.
- D. C<sub>L</sub> is the instrumentation and fixture capacitance within 2 cm of the DUT and 20%.

Figure 11. Receiver Enable/Disable Time Test Circuit and Waveforms

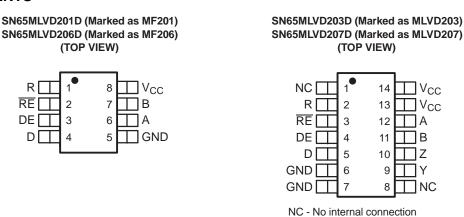




- A. All input pulses are supplied by an Agilent 8304A Stimulus System.
- B. The measurement is made on a TEK TDS6604 running TDSJIT3 application software
- C. Period jitter is measured using a 100 MHz 50 1% duty cycle clock input.
- D. Peak-to-peak jitter is measured using a 200 Mbps 2<sup>15</sup>-1 PRBS input.

Figure 12. Receiver Jitter Measurement Waveforms

### **PIN ASSIGNMENTS**





# **DEVICE FUNCTION TABLES**

**TYPE-1 RECEIVER (201, 203)** 

INPUTS	OUTPUT	
$V_{ID} = V_A - V_B$	RE	R
V <sub>ID</sub> ≥ 50 mV	L	Н
$-50 \text{ mV} < V_{\text{ID}} < 50 \text{ mV}$	L	?
$V_{ID} \le -50 \text{ mV}$	L	L
X	Н	Z
X	Open	Z
Open Circuit	L	?

**TYPE-2 RECEIVER (206, 207)** 

INPUTS	OUTPUT	
$V_{ID} = V_A - V_B$	RE	R
V <sub>ID</sub> ≥ 150 mV	L	Н
50 mV < V <sub>ID</sub> < 150 mV	L	?
$V_{ID} \le 50 \text{ mV}$	L	L
X	Н	Z
X	Open	Z
Open Circuit	L	L

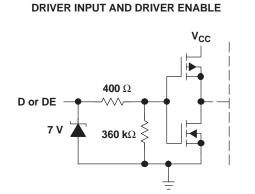
#### **DRIVER**

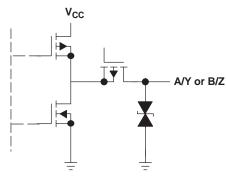
INPUT	ENABLE	OUTF	PUTS
D	DE	A OR Y	B OR Z
L	Н	L	Н
H	Н	Н	L
OPEN	Н	L	Н
X	OPEN	Z	Z
X	L	Z	Z

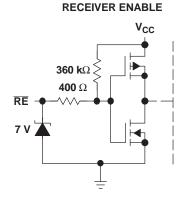
H = high level, L = low level, Z = high impedance, X = Don't care, ? = indeterminate

### **EQUIVALENT INPUT AND OUTPUT SCHEMATIC DIAGRAMS**

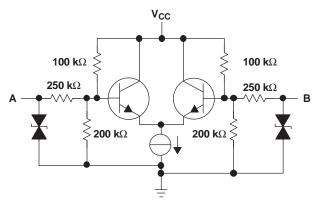
# **DRIVER OUTPUT**



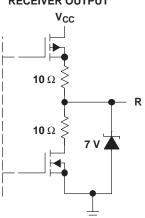




# **RECEIVER INPUT**

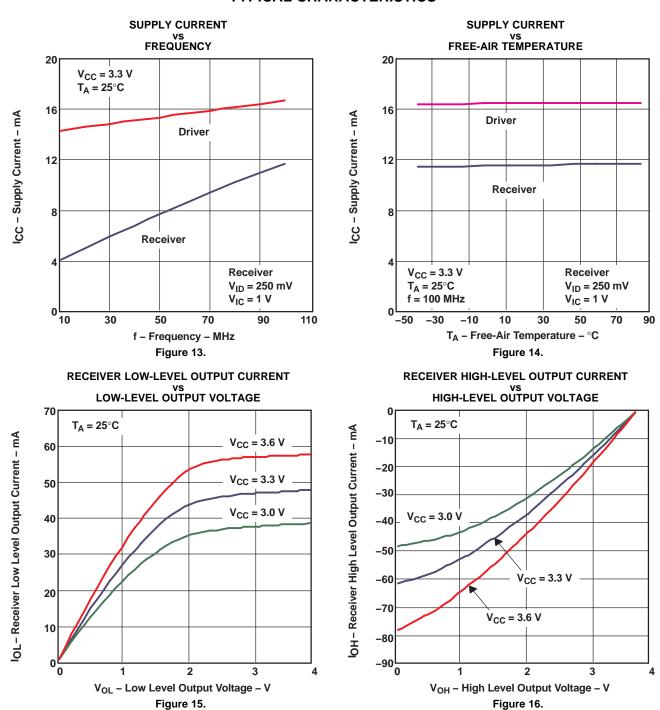


### **RECEIVER OUTPUT**



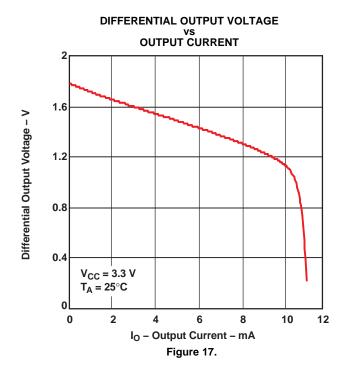


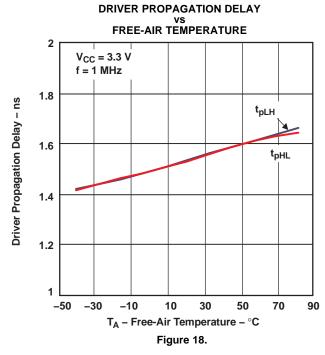
#### TYPICAL CHARACTERISTICS

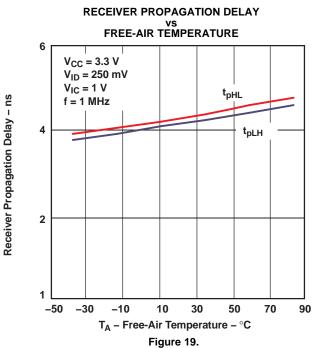


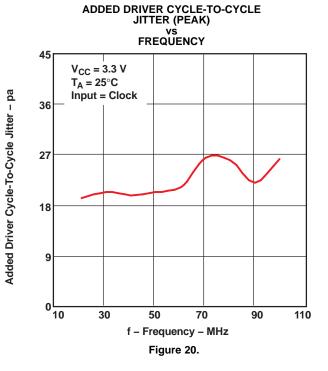


# **TYPICAL CHARACTERISTICS (continued)**



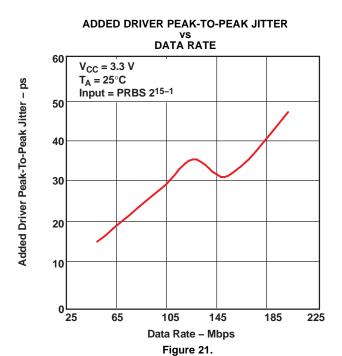


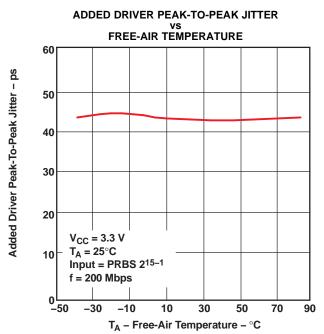






# **TYPICAL CHARACTERISTICS (continued)**





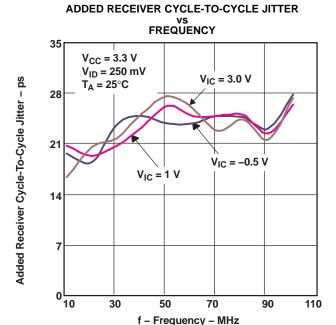
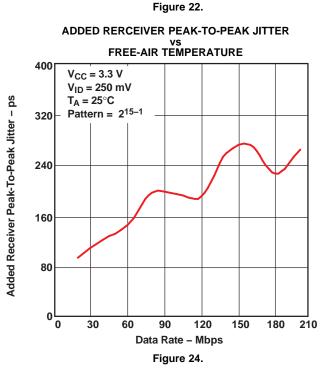
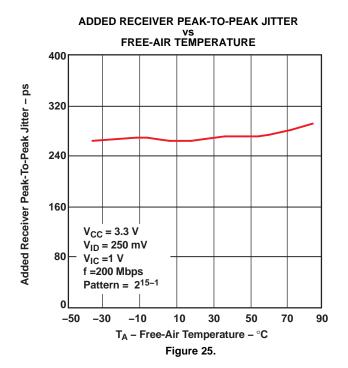


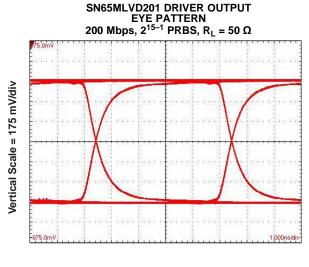
Figure 23.





# **TYPICAL CHARACTERISTICS (continued)**

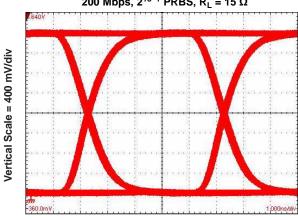




Horizontal Scale = 1 ns/div

Figure 26.





Horizontal Scale = 1 ns/div Figure 27.



#### **APPLICATION INFORMATION**

#### Receiver Input Threshold (Failsafe)

The MLVD standard defines a type 1 and type 2 receiver. Type 1 receivers include no provisions for failsafe and have their differential input voltage thresholds near zero volts. Type 2 receivers have their differential input voltage thresholds offset from zero volts to detect the absence of a voltage difference. The impact to receiver output by the offset input can be seen in Table 3 and Figure 28.

**Table 3. Receiver Input Voltage Threshold Requirements** 

RECEIVER TYPE	OUTPUT LOW	OUTPUT HIGH
Type 1	$-2.4 \text{ V} \le \text{V}_{\text{ID}} \le -0.05 \text{ V}$	$0.05 \text{ V} \le \text{V}_{\text{ID}} \le 2.4 \text{ V}$
Type 2	$-2.4 \text{ V} \le \text{V}_{\text{ID}} \le 0.05 \text{ V}$	0.15 V ≤ V <sub>ID</sub> ≤ 2.4 V

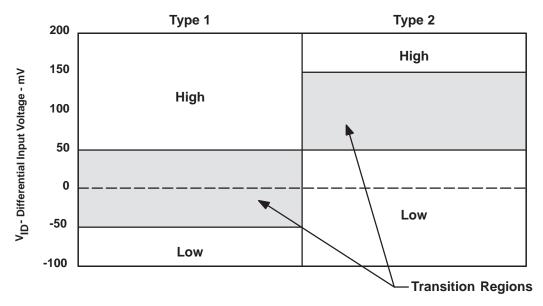


Figure 28. Expanded Graph of Receiver Differential Input Voltage Showing Transition Region



#### LIVE INSERTION/GLITCH-FREE POWER UP/DOWN

The SN65MLVD201/203/206/207 family of products offered by Texas Instruments provides a glitch-free powerup/down feature that prevents the M-LVDS outputs of the device from turning on during a powerup or powerdown event. This is especially important in live insertion applications, when a device is physically connected to an M-LVDS multipoint bus and VCC is ramping.

While the M-LVDS interface for these devices is glitch free on powerup/down, the receiver output structure is not.Figure 29 shows the performance of the receiver output pin, R (CHANNEL 2), as Vcc (CHANNEL 1) is ramped.

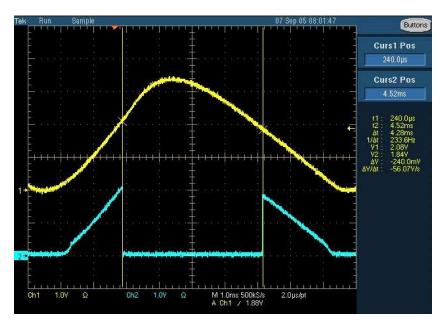


Figure 29. M-LVDS Receiver Output: VCC (CHANNEL 1), R Pin (CHANNEL 2)

The glitch on the R pin is independent of the  $\overline{\text{RE}}$  voltage. Any complications or issues from this glitch are easily resolved in power sequencing or system requirements that suspend operation until VCC has reached a steady state value.





10-Dec-2020

#### PACKAGING INFORMATION

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan	Lead finish/ Ball material	MSL Peak Temp	Op Temp (°C)	Device Marking (4/5)	Samples
SN65MLVD201D	ACTIVE	SOIC	D	8	75	RoHS & Green	NIPDAU	Level-1-260C-UNLIM	-40 to 85	MF201	Samples
SN65MLVD201DG4	ACTIVE	SOIC	D	8	75	RoHS & Green	NIPDAU	Level-1-260C-UNLIM	-40 to 85	MF201	Samples
SN65MLVD201DR	ACTIVE	SOIC	D	8	2500	RoHS & Green	NIPDAU	Level-1-260C-UNLIM	-40 to 85	MF201	Samples
SN65MLVD203D	ACTIVE	SOIC	D	14	50	RoHS & Green	NIPDAU	Level-1-260C-UNLIM	-40 to 85	MLVD203	Samples
SN65MLVD203DG4	ACTIVE	SOIC	D	14	50	RoHS & Green	NIPDAU	Level-1-260C-UNLIM	-40 to 85	MLVD203	Samples
SN65MLVD203DR	ACTIVE	SOIC	D	14	2500	RoHS & Green	NIPDAU	Level-1-260C-UNLIM	-40 to 85	MLVD203	Samples
SN65MLVD206D	ACTIVE	SOIC	D	8	75	RoHS & Green	NIPDAU	Level-1-260C-UNLIM	-40 to 85	MF206	Samples
SN65MLVD206DG4	ACTIVE	SOIC	D	8	75	RoHS & Green	NIPDAU	Level-1-260C-UNLIM	-40 to 85	MF206	Samples
SN65MLVD206DR	ACTIVE	SOIC	D	8	2500	RoHS & Green	NIPDAU	Level-1-260C-UNLIM	-40 to 85	MF206	Samples
SN65MLVD207D	ACTIVE	SOIC	D	14	50	RoHS & Green	NIPDAU	Level-1-260C-UNLIM	-40 to 85	MLVD207	Samples
SN65MLVD207DG4	ACTIVE	SOIC	D	14	50	RoHS & Green	NIPDAU	Level-1-260C-UNLIM	-40 to 85	MLVD207	Samples
SN65MLVD207DR	ACTIVE	SOIC	D	14	2500	RoHS & Green	NIPDAU	Level-1-260C-UNLIM	-40 to 85	MLVD207	Samples

<sup>(1)</sup> The marketing status values are defined as follows:

**ACTIVE:** Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

(2) RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

**Green:** TI defines "Green" to mean the content of Chlorine (Cl) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.



# **PACKAGE OPTION ADDENDUM**

10-Dec-2020

- (3) MSL, Peak Temp. The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.
- (4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.
- (5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.
- (6) Lead finish/Ball material Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

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# **PACKAGE MATERIALS INFORMATION**

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# TAPE AND REEL INFORMATION



# 

A0	Dimension designed to accommodate the component width
В0	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

### QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



#### \*All dimensions are nominal

Device	Package Type	Package Drawing		SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
SN65MLVD201DR	SOIC	D	8	2500	330.0	12.4	6.4	5.2	2.1	8.0	12.0	Q1
SN65MLVD203DR	SOIC	D	14	2500	330.0	16.4	6.5	9.0	2.1	8.0	16.0	Q1
SN65MLVD206DR	SOIC	D	8	2500	330.0	12.4	6.4	5.2	2.1	8.0	12.0	Q1
SN65MLVD207DR	SOIC	D	14	2500	330.0	16.4	6.5	9.0	2.1	8.0	16.0	Q1



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### \*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
SN65MLVD201DR	SOIC	D	8	2500	353.0	353.0	32.0
SN65MLVD203DR	SOIC	D	14	2500	333.2	345.9	28.6
SN65MLVD206DR	SOIC	D	8	2500	353.0	353.0	32.0
SN65MLVD207DR	SOIC	D	14	2500	340.5	336.1	32.0

# **PACKAGE MATERIALS INFORMATION**

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# **TUBE**



\*All dimensions are nominal

Device	Package Name	Package Type	Pins	SPQ	L (mm)	W (mm)	T (µm)	B (mm)
SN65MLVD201D	D	SOIC	8	75	507	8	3940	4.32
SN65MLVD201DG4	D	SOIC	8	75	507	8	3940	4.32
SN65MLVD203D	D	SOIC	14	50	507	8	3940	4.32
SN65MLVD203DG4	D	SOIC	14	50	507	8	3940	4.32
SN65MLVD206D	D	SOIC	8	75	507	8	3940	4.32
SN65MLVD206DG4	D	SOIC	8	75	507	8	3940	4.32
SN65MLVD207D	D	SOIC	14	50	507	8	3940	4.32
SN65MLVD207DG4	D	SOIC	14	50	507	8	3940	4.32





#### NOTES:

- 1. All linear dimensions are in millimeters. Dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.

  2. This drawing is subject to change without notice.

  3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not
- exceed 0.15 mm, per side.
- 4. This dimension does not include interlead flash. Interlead flash shall not exceed 0.43 mm, per side.
- 5. Reference JEDEC registration MS-012, variation AB.





NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.

7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.





NOTES: (continued)

- 8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
- 9. Board assembly site may have different recommendations for stencil design.







# NOTES:

- 1. Linear dimensions are in inches [millimeters]. Dimensions in parenthesis are for reference only. Controlling dimensions are in inches. Dimensioning and tolerancing per ASME Y14.5M.
- 2. This drawing is subject to change without notice.
- 3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed .006 [0.15] per side.
- 4. This dimension does not include interlead flash.
- 5. Reference JEDEC registration MS-012, variation AA.





NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.

7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.





#### NOTES: (continued)

- 8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
- 9. Board assembly site may have different recommendations for stencil design.



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